

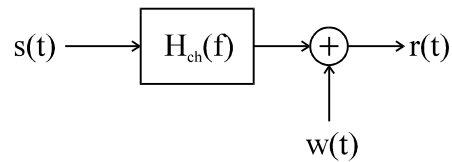
Equalization in digital communication

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Intersymbol interference (1)

Dispersive (frequency-selective) channel



$H_{ch}(f)$: channel transfer function (often unknown)

$w(t)$: AWGN

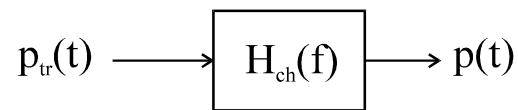
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Intersymbol interference (2)

Linear modulation

$$s(t) = \sqrt{E_s} \sum_k a_k p_{tr}(t - kT)$$

$$r(t) = \sqrt{E_s} \sum_m a_m p(t - mT) + w(t)$$

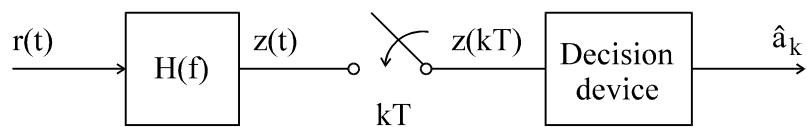


$$P(f) = H_{ch}(f)P_{tr}(f)$$

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Intersymbol interference (3)

Receiver



$$z(kT) = \underbrace{\sqrt{E_s} a_k g(0)}_{\text{useful term}} + \underbrace{\sqrt{E_s} \sum_{m \neq 0} a_{k-m} g(mT)}_{\text{intersymbol interference term (ISI)}} + \underbrace{n(kT)}_{\text{noise term}}$$

$$G(f) = H(f)P(f) = H(f)H_{ch}(f)P_{tr}(f)$$

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Intersymbol interference (4)

Receiver (cont.)

$$\frac{P_{\text{noise}}}{P_{\text{useful}}} = \frac{N_0}{E_s |g(0)|^2} \int_{-\infty}^{+\infty} |H(f)|^2 df$$

is minimum for $H(f) = P_{\text{tr}}^*(f) H_{\text{ch}}^*(f)$ (matched filter)

$$\frac{P_{\text{ISI}}}{P_{\text{useful}}} = \frac{1}{|g(0)|^2} \sum_{m \neq 0} |g(mT)|^2$$

is zero when $G(f)$ fulfills the Nyquist criterion

In general, the matched filter does not yield zero ISI

Intersymbol interference (5)

Eye diagram

Eye diagram shows $\text{Re} \left[\sum_m a_m g(t - mT) \right]$

as a function of time for all possible data sequences

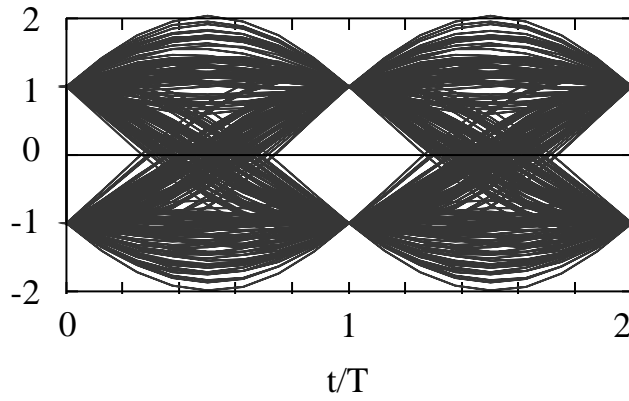
Eye diagram is periodic in t with period T

M-PAM : $g(t)$ has duration LT

\Rightarrow eye diagram has M^L lines per period

Intersymbol interference (6)

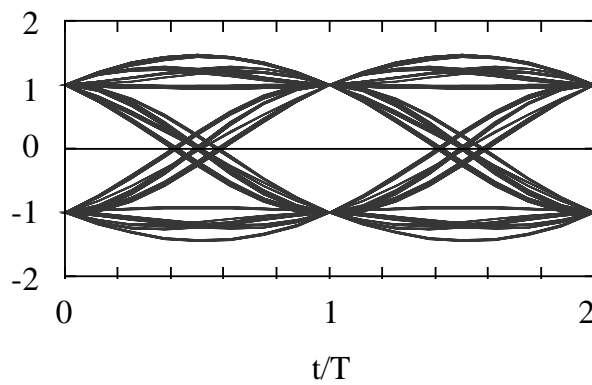
Eye diagram 20 % cosine rolloff pulse



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Intersymbol interference (7)

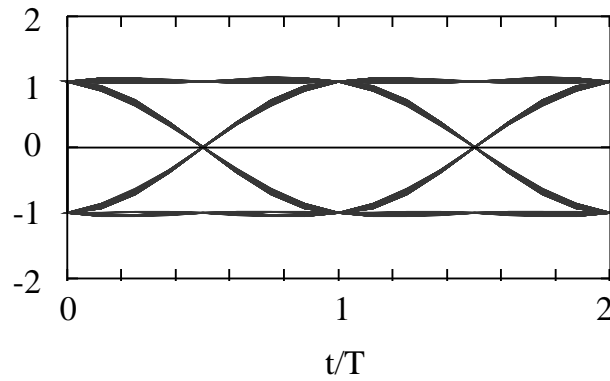
Eye diagram 50 % cosine rolloff pulse



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Intersymbol interference (8)

Eye diagram 100 % cosine rolloff pulse



9

Intersymbol interference (9)

Scatter diagram

For a given sampling instant kT , scatter diagram shows

$$\sum_m a_m g(kT - mT) = a_k g(0) + \sum_{m \neq 0} a_{k-m} g(mT)$$

in the complex plane for all possible data sequences

Constellation of M points : $g(t)$ has duration LT

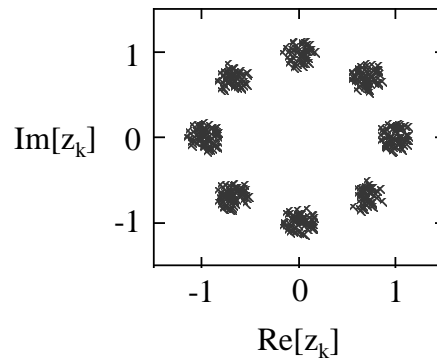
\Rightarrow scatter diagram has M^L points

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Intersymbol interference (10)

Scatter diagram (cont.)

50 % cosine rolloff pulse, $T/10$ sampling error, 8-PSK



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Intersymbol interference (11)

Intersymbol interference power

$$\sum_{m=-\infty}^{+\infty} g(mT) \exp(-j2\pi f m T) = \frac{1}{T} \sum_{k=-\infty}^{+\infty} G\left(f + \frac{k}{T}\right) = G_{\text{fld}}\left(e^{j2\pi f T}\right)$$

“folding” of $G(f)$ yields $G_{\text{fld}}(\exp(j2\pi f T))$ which is periodic in f with period $1/T$

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Intersymbol interference (12)

Intersymbol interference power (cont.)

Notation :

$$\langle X(e^{j2\pi fT}) \rangle = T \int_{-\frac{1}{2T}}^{\frac{1}{2T}} X(e^{j2\pi fT}) df$$

(averaging over interval $(-1/(2T), 1/(2T))$)

Intersymbol interference (13)

Intersymbol interference power (cont.)

$$g(mT) = \langle G_{fld}(e^{j2\pi fT}) \exp(j2\pi fmT) \rangle$$

$$g(0) = \langle G_{fld}(e^{j2\pi fT}) \rangle$$

$$\sum_m |g(mT)|^2 = \langle |G_{fld}(e^{j2\pi fT})|^2 \rangle$$

Intersymbol interference (14)

Intersymbol interference power (cont.)

$$\frac{P_{\text{ISI}}}{P_{\text{useful}}} = \frac{\left\langle \left| G_{\text{fld}}(e^{j2\pi fT}) - \langle G_{\text{fld}}(e^{j2\pi fT}) \rangle \right|^2 \right\rangle}{\left| \langle G_{\text{fld}}(e^{j2\pi fT}) \rangle \right|^2}$$

$$= \frac{\text{power of fluctuation of } G_{\text{fld}}(e^{j2\pi fT}) \text{ about its mean}}{\left| \text{mean of } G_{\text{fld}}(e^{j2\pi fT}) \right|^2}$$

Intersymbol interference (15)

Intersymbol interference power (cont.)

Zero ISI is obtained when

$$G_{\text{fld}}(e^{j2\pi fT}) = \text{constant} \quad (\text{Nyquist criterion})$$

“Equalization” : elimination (or reduction) of ISI

Intersymbol interference (16)

Example

Transmit pulse : $P(f) = 50\%$ square-root cosine rolloff

Channel : direct path + reflection

$$H_{ch}(f) = 1 + b \exp(-j2\pi f\tau)$$

reflection : delay τ , magnitude b ($0 < b < 1$)

$$\text{ripple [dB]} = 20 \log\left(\frac{1+b}{1-b}\right)$$

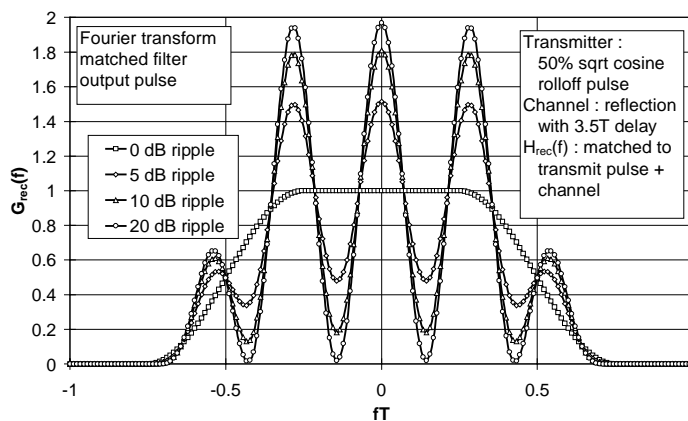
Receive filter : matched to transmit pulse + channel

$$H_{rec}(f) = P^*(f)H_{ch}^*(f)$$

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Intersymbol interference (17)

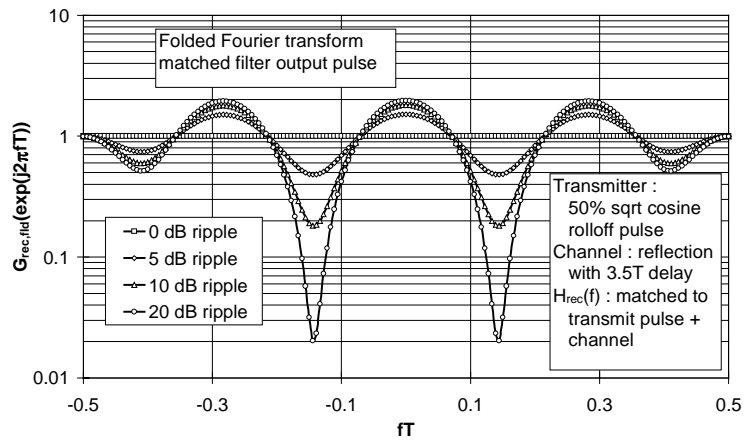
Example (cont.)



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Intersymbol interference (18)

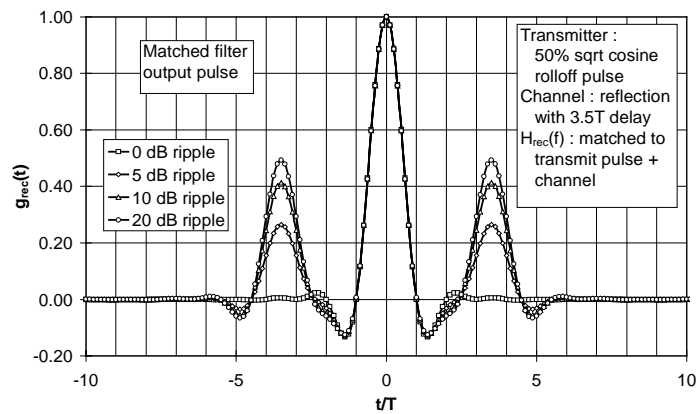
Example (cont.)



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Intersymbol interference (19)

Example (cont.)

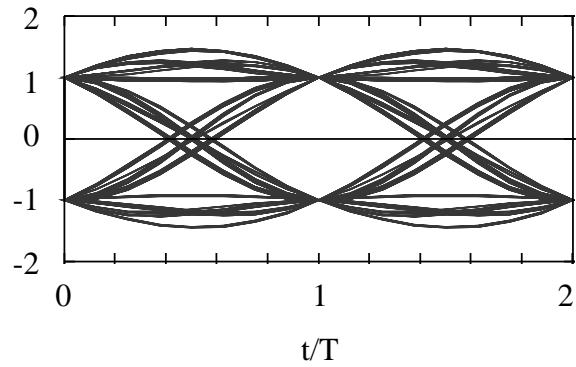


20

Intersymbol interference (20)

Example (cont.)

Eye diagram at matched filter output (0 dB ripple)

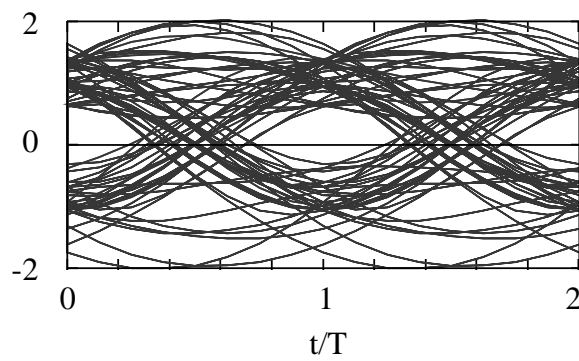


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Intersymbol interference (21)

Example (cont.)

Eye diagram at matched filter output (5 dB ripple)

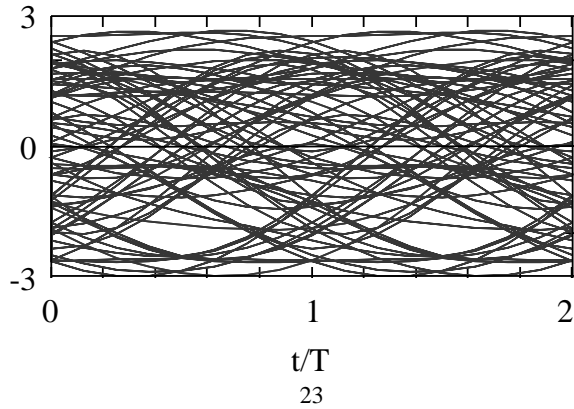


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Intersymbol interference (22)

Example (cont.)

Eye diagram at matched filter output (10 dB ripple)



Intersymbol interference (23)

Example (cont.)

Ripple [dB]	$\frac{P_{ISI}}{P_{useful}}$ [dB]
0	$-\infty$
5	-9.96
10	-6.03
15	-4.84
20	-4.47

Zero-forcing linear equalizer (ZF-LE) (1)

Equalizer structure

Decompose the receive filter as

$$H(f) = \underbrace{H_{\text{rec}}(f)}_{\substack{\text{analog} \\ \text{prefilter}}} \underbrace{C(\exp(j2\pi fT))}_{\text{linear equalizer}}$$

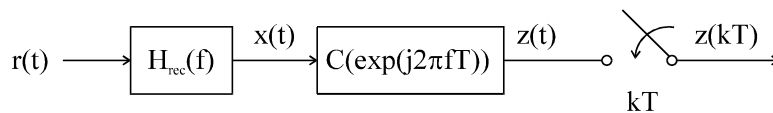
$$C(e^{j2\pi fT}) = \sum_{m=-\infty}^{+\infty} c_m \exp(j2\pi fmT)$$

c_m : m-th equalizer tap

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Zero-forcing linear equalizer (2)

Equalizer structure (cont.)



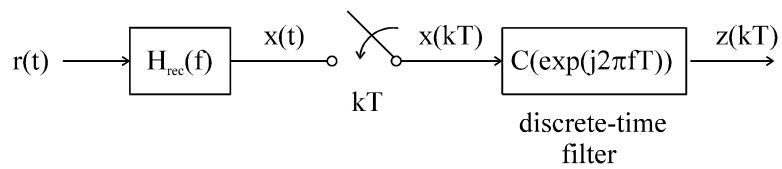
$$z(t) = \sum_{m=-\infty}^{+\infty} c_m x(t - mT) \quad z(kT) = \sum_{m=-\infty}^{+\infty} c_m x(kT - mT)$$

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Zero-forcing linear equalizer (3)

Equalizer structure (cont.)

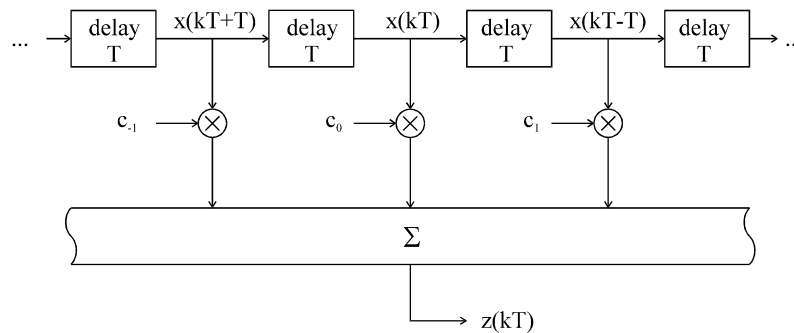
$$z(kT) = \sum_{m=-\infty}^{+\infty} c_m x(kT - mT)$$



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Zero-forcing linear equalizer (4)

Equalizer structure (cont.)



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Zero-forcing linear equalizer (5)

Equalizer transfer function

The zero-forcing linear equalizer should be selected such that the resulting $G_{\text{fld}}(\exp(j2\pi fT))$ is constant (“equalized”), in order to eliminate all ISI

$$G(f) = \underbrace{P_{\text{tr}}(f)H_{\text{ch}}(f)H_{\text{rec}}(f)}_{G_{\text{rec}}(f)} \underbrace{C(\exp(j2\pi fT))}_{\substack{\text{periodic in } f, \\ \text{period } 1/T}}$$

$$G_{\text{fld}}(e^{j2\pi fT}) = G_{\text{rec, fld}}(e^{j2\pi fT})C(e^{j2\pi fT})$$

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Zero-forcing linear equalizer (6)

Equalizer transfer function (cont.)

$$\Rightarrow C(e^{j2\pi fT}) = \frac{1}{G_{\text{rec, fld}}(e^{j2\pi fT})}$$

The ZF-LE is not unique : different choice of $H_{\text{rec}}(f)$ yields a different equalizer and a different $P_{\text{noise}}/P_{\text{useful}}$

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Zero-forcing linear equalizer (7)

Optimum zero-forcing linear equalizer

$H(f)$ minimizes $P_{\text{noise}}/P_{\text{useful}}$, under the restriction of zero ISI

$$\text{Solution : } H(f) = \underbrace{P_{\text{tr}}^*(f)H_{\text{ch}}^*(f)}_{\text{matched filter}} \underbrace{C(\exp(j2\pi fT))}_{\text{linear equalizer}}$$

$$C(e^{j2\pi fT}) = \frac{1}{G_{\text{rec, fld}}(e^{j2\pi fT})}$$

$$G_{\text{rec}}(f) = |P_{\text{tr}}(f)H_{\text{ch}}(f)|^2$$

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Zero-forcing linear equalizer (8)

Noise enhancement

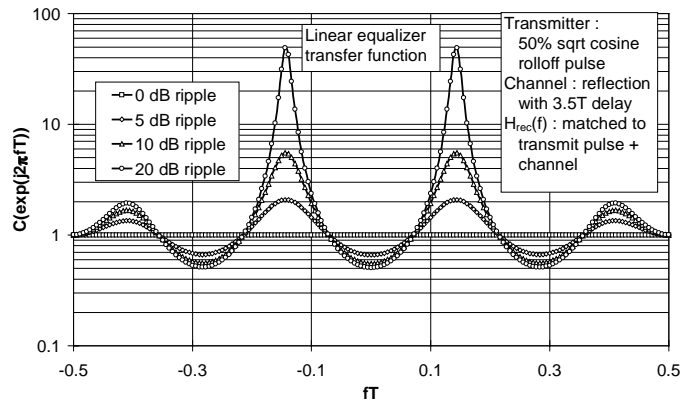
As $H(f)$ for the optimum ZF-LE is different from the matched filter, the equalizer eliminates ISI at the expense of an increased noise level

$$\left(\frac{P_{\text{noise}}}{P_{\text{useful}}} \right)_{\text{matched filter}} < \left(\frac{P_{\text{noise}}}{P_{\text{useful}}} \right)_{\text{ZF-LE}}$$

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Zero-forcing linear equalizer (9)

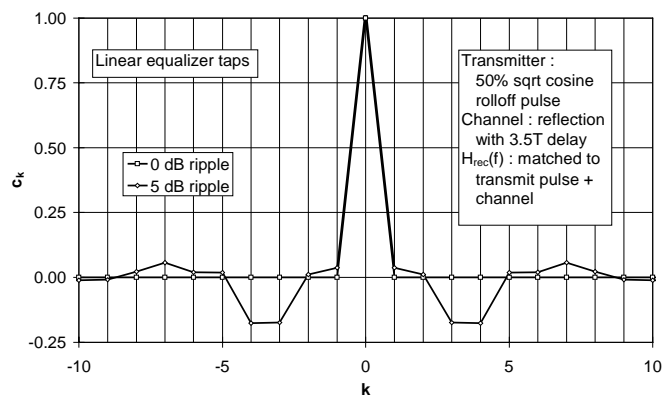
Example Channel : direct path + reflection



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Zero-forcing linear equalizer (10)

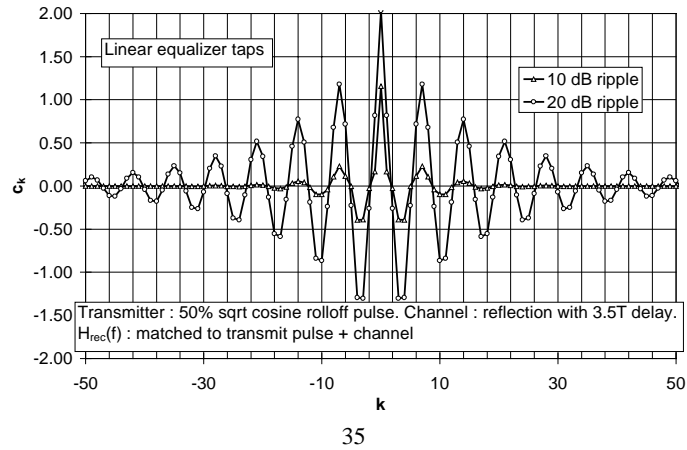
Example (cont.)



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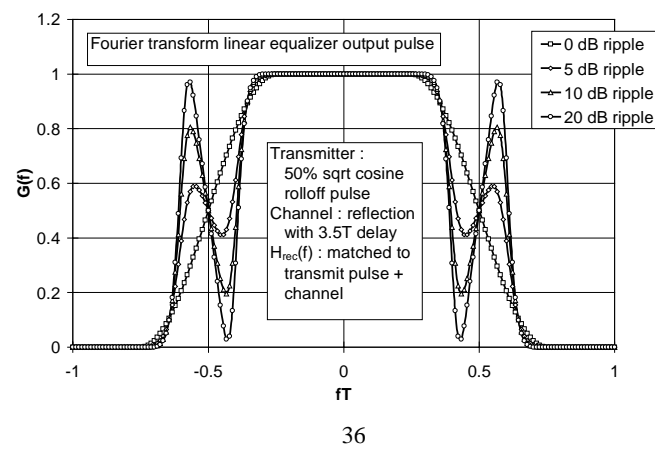
Zero-forcing linear equalizer (11)

Example (cont.)



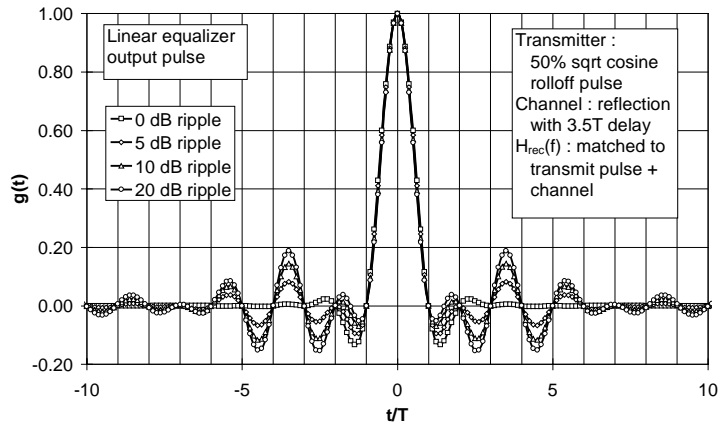
Zero-forcing linear equalizer (12)

Example (cont.)



Zero-forcing linear equalizer (13)

Example (cont.)

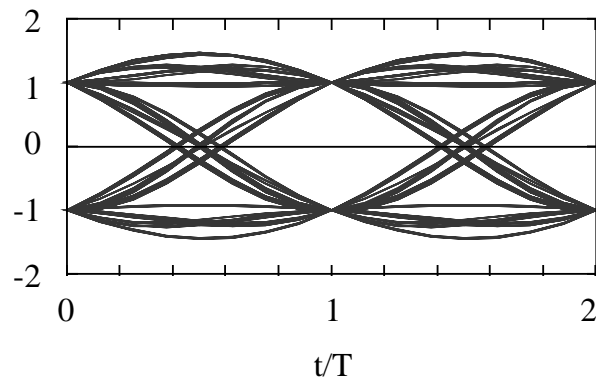


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Zero-forcing linear equalizer (14)

Example (cont.)

Eye diagram at equalizer output (0 dB ripple)

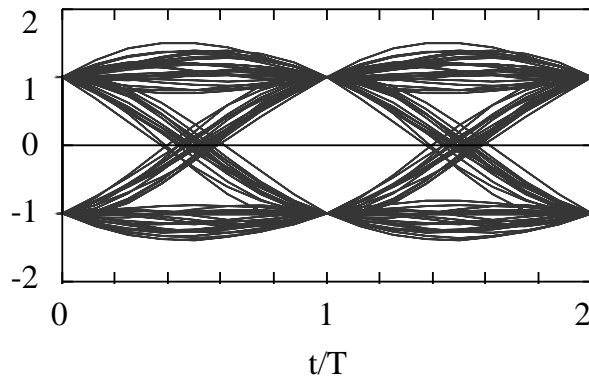


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Zero-forcing linear equalizer (15)

Example (cont.)

Eye diagram at equalizer output (5 dB ripple)

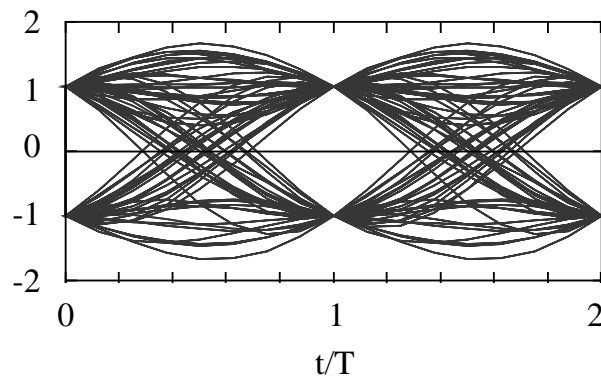


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Zero-forcing linear equalizer (16)

Example (cont.)

Eye diagram at equalizer output (10 dB ripple)

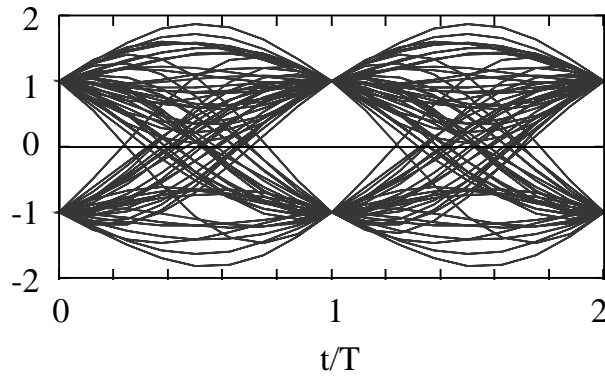


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Zero-forcing linear equalizer (17)

Example (cont.)

Eye diagram at equalizer output (20 dB ripple)



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Zero-forcing linear equalizer (18)

Example (cont.)

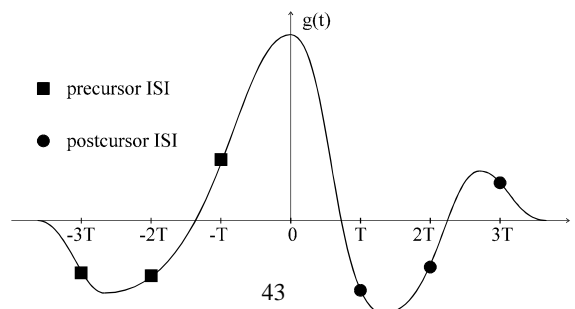
Ripple [dB]	Noise enhancement [dB] (ZF-LE)
0	0
5	0.49
10	1.7
15	3.36
20	5.33

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Zero-forcing decision-feedback equalizer (ZF-DFE) (1)

Equalizer structure

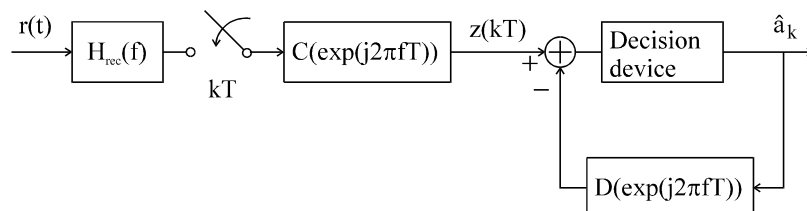
$$\text{ISI}(kT) = \underbrace{\sqrt{E_s} \sum_{m>0} a_{k-m} g(mT)}_{\text{postcursor ISI (past symbols)}} + \underbrace{\sqrt{E_s} \sum_{m<0} a_{k-m} g(mT)}_{\text{precursor ISI (future symbols)}}$$



Zero-forcing decision-feedback equalizer (2)

Equalizer structure (cont.)

Forward equalizer $C(\exp(j2\pi fT))$ eliminates precursor ISI
 Feedback equalizer $D(\exp(j2\pi fT))$ is a causal filter, using past decisions to cancel postcursor ISI



Zero-forcing decision-feedback equalizer

(3)

Equalizer transfer function

$$C(e^{j2\pi fT}) = \sum_{m=-\infty}^{+\infty} c_m e^{j2\pi fT} \quad D(e^{j2\pi fT}) = \sum_{m=1}^{+\infty} d_m e^{-j2\pi fT}$$

$$G_{\text{fld}}(e^{j2\pi fT}) = G_{\text{rec, fld}}(e^{j2\pi fT}) C(e^{j2\pi fT})$$

Requirement for zero ISI :

$$G_{\text{fld}}(e^{j2\pi fT}) = 1 + D(e^{j2\pi fT})$$

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Zero-forcing decision-feedback equalizer

(4)

Equalizer transfer function (cont.)

$$\Rightarrow C(e^{j2\pi fT}) = \frac{1 + D(e^{j2\pi fT})}{G_{\text{rec}}(e^{j2\pi fT})}$$

The ZF-DFE is not unique : different choice of $H_{\text{rec}}(f)$ and $D(\exp(j2\pi fT))$ yields a different equalizer and a different $P_{\text{noise}}/P_{\text{useful}}$

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Zero-forcing decision-feedback equalizer (5)

Optimum zero-forcing decision-feedback equalizer

$H(f)$ minimizes $P_{\text{noise}}/P_{\text{useful}}$, under the restriction of zero precursor ISI

Solution

$$H(f) = \underbrace{P_{\text{tr}}^*(f)H_{\text{ch}}^*(f)}_{\text{matched filter}} \underbrace{C(\exp(j2\pi fT))}_{\text{forward equalizer}}$$

Zero-forcing decision-feedback equalizer (6)

Optimum zero-forcing decision-feedback equalizer (cont.)

$$G_{\text{rec}}(f) = |H_{\text{ch}}(f)|^2 |P(f)|^2 > 0$$

$$\Rightarrow g_{\text{rec}}(t) = g_{\text{rec}}^*(-t) \Rightarrow g_{\text{rec}}(mT) = g_{\text{rec}}^*(-mT)$$

$$G_{\text{rec, fld}}(z) = \sum_{m=-\infty}^{+\infty} g_{\text{rec}}(mT)z^{-m} = G_{\text{rec, fld}}^*\left(\frac{1}{z^*}\right)$$

poles and zeroes of $G_{\text{rec, fld}}(z)$ occur in pairs :
 z_p and $1/z_p^*$ (poles), z_n and $1/z_n^*$ (zeroes)

Zero-forcing decision-feedback equalizer

(7)

Optimum zero-forcing decision-feedback equalizer (cont.)

“Spectral factorization” : $G_{\text{rec, fld}}(z) = K B(z) B^*\left(\frac{1}{z^*}\right)$

$K > 0$

$$B(z) = \frac{\prod_i (1 - z_{n,i} z^{-1})}{\prod_j (1 - z_{p,j} z^{-1})} = 1 + \sum_{m=1}^{+\infty} b_m z^{-m} \quad (\text{causal}) \quad \begin{array}{l} \text{poles and zeroes} \\ \text{inside unit circle} \end{array}$$

$$B^*\left(\frac{1}{z^*}\right) = \frac{\prod_i (1 - z_{n,i}^* z)}{\prod_j (1 - z_{p,j}^* z)} = 1 + \sum_{m=1}^{+\infty} b_m^* z^m \quad (\text{anti-causal}) \quad \begin{array}{l} \text{poles and zeroes} \\ \text{outside unit circle} \end{array}$$

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Zero-forcing decision-feedback equalizer

(8)

Optimum zero-forcing decision-feedback equalizer (cont.)

$$C(e^{j2\pi fT}) = \frac{1}{K B^*(e^{j2\pi fT})} \quad (\text{anti-causal})$$

$$\Rightarrow G_{\text{fld}}(e^{j2\pi fT}) = B(e^{j2\pi fT}) \quad (\text{causal})$$

$$D(e^{j2\pi fT}) = B(e^{j2\pi fT}) - 1 \quad (\text{causal})$$

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Zero-forcing decision-feedback equalizer (9)

Noise enhancement

As $H(f)$ for the optimum ZF-DFE is different from the matched filter, the equalizer eliminates ISI at the expense of an increased noise level. The noise enhancement is less than for the optimum ZF-LE

$$\left(\frac{P_{\text{noise}}}{P_{\text{useful}}} \right)_{\text{matched filter}} < \left(\frac{P_{\text{noise}}}{P_{\text{useful}}} \right)_{\text{ZF-DFE}} < \left(\frac{P_{\text{noise}}}{P_{\text{useful}}} \right)_{\text{ZF-LE}}$$

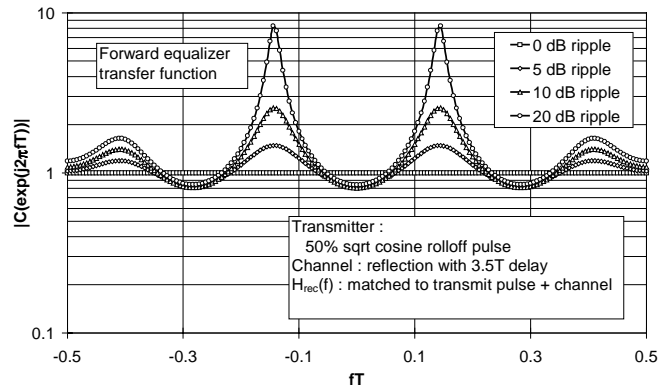
Zero-forcing decision-feedback equalizer (10)

Error propagation in DFE

Cancellation of postcursor ISI assumes correct symbol decisions. Erroneous symbol decisions enhance postcursor ISI, which in turn may give rise to additional decision errors

Zero-forcing decision-feedback equalizer (11)

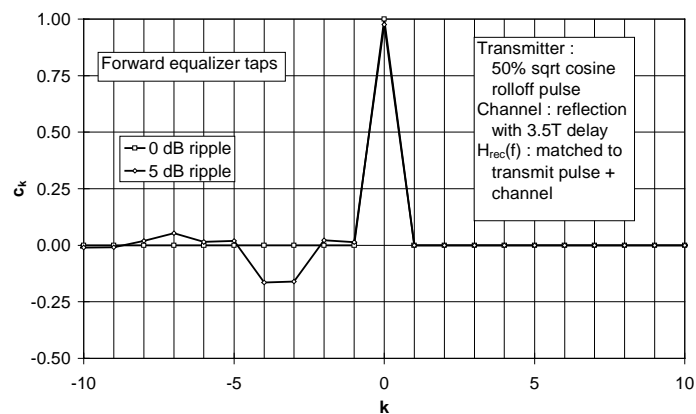
Example Channel : direct path + reflection



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Zero-forcing decision-feedback equalizer (12)

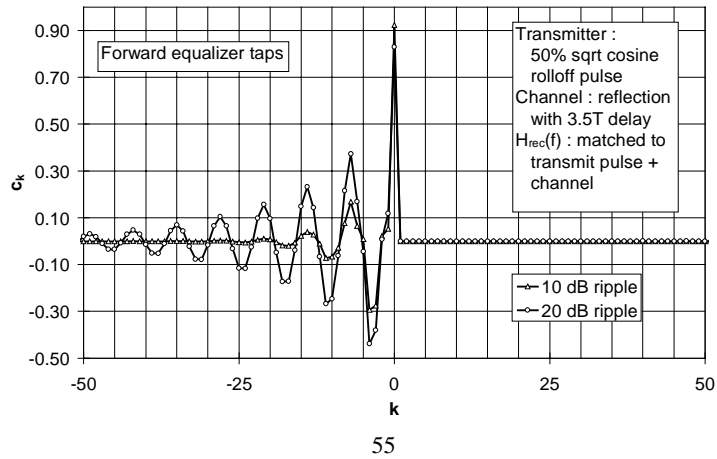
Example (cont.)



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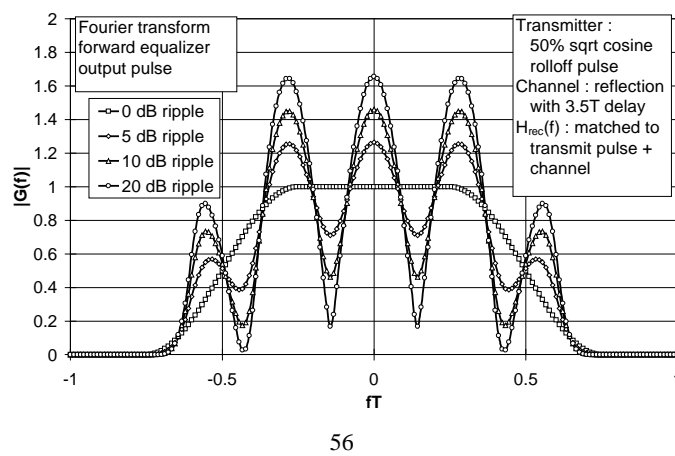
Zero-forcing decision-feedback equalizer (13)

Example (cont.)



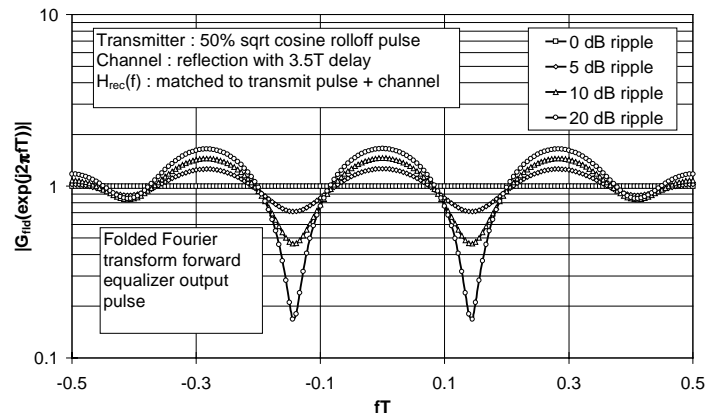
Zero-forcing decision-feedback equalizer (14)

Example (cont.)



Zero-forcing decision-feedback equalizer (15)

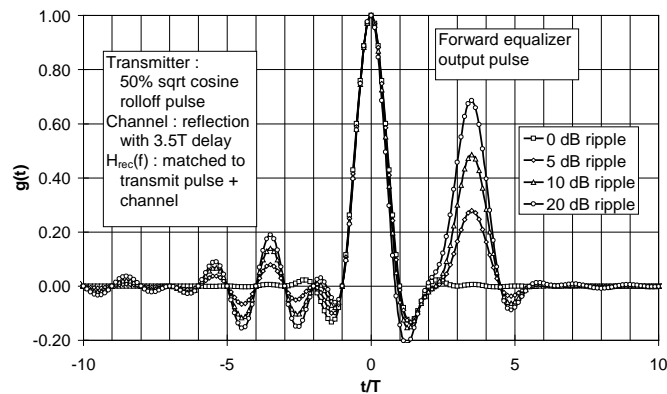
Example (cont.)



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Zero-forcing decision-feedback equalizer (16)

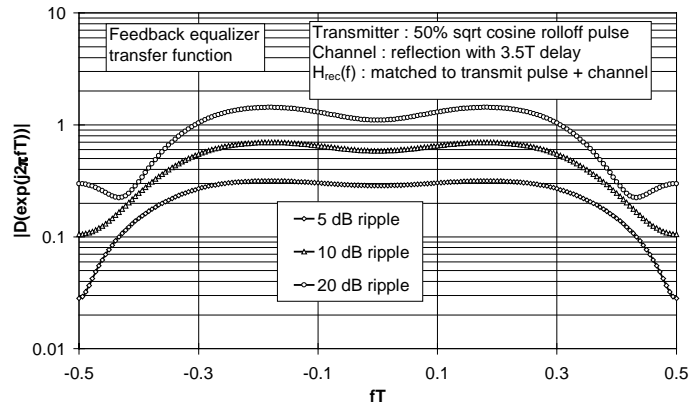
Example (cont.)



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Zero-forcing decision-feedback equalizer (17)

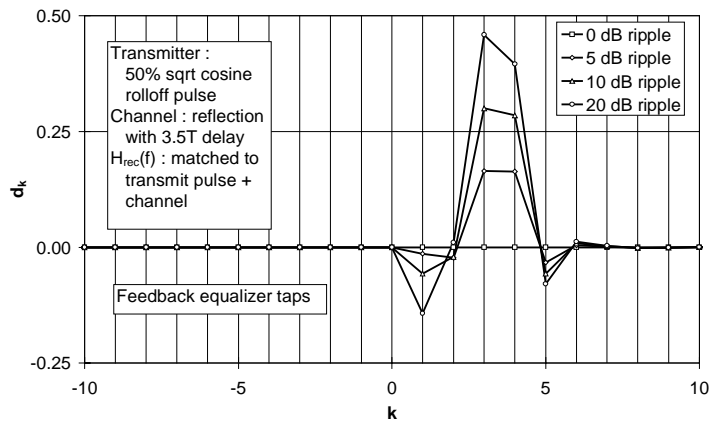
Example (cont.)



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Zero-forcing decision-feedback equalizer (18)

Example (cont.)



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Zero-forcing decision-feedback equalizer (19)

Example (cont.)

Ripple [dB]	Noise enhancement [dB] (ZF-DFE)
0	0
5	0.24
10	0.71
15	1.14
20	1.44