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K := 220           α := 0.015           offset := π / 180
var_theta := 0.1
K_P := 20

N := 10          saw(x) := x - 2 · π · floor(x / (2 · π)) + 1 / 2

L := 1000
i := 0 .. K_P - 1
m := 0 .. L - 1
k := 0 .. K - 1
n := 0 .. N - 1

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basisfuncties

$$\psi_{k,n} := \text{if } n > 0, \sqrt{\frac{2}{K}} \cdot \cos\left[\frac{\pi \cdot n}{K} \cdot \left(k + \frac{1}{2}\right)\right], \sqrt{\frac{1}{K}}$$

$$\text{index}_i := \frac{(2 \cdot i + 1) \cdot K - K_P}{2 \cdot K_P}$$

$$\psi_{i,n} := \psi(\text{index}_i), n$$

faseruis

$$w_\theta := \text{rnorm}(K \cdot L, 0, 1)$$

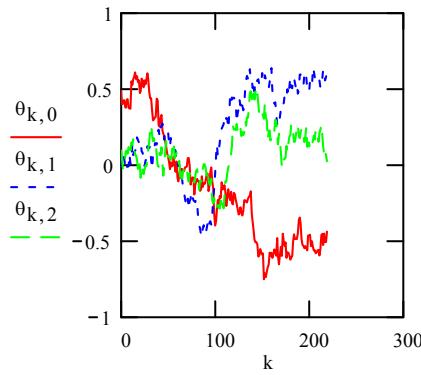
$$\theta := \text{rnorm}(L, 0, \sqrt{\text{var}_\theta})$$

$$\theta_{0,m} := \theta_m$$

$$\theta_{k+1,m} := (1 - \alpha) \cdot \theta_{k,m} + w_\theta_{m \cdot K + k} \cdot \sqrt{(2 - \alpha) \cdot \alpha \cdot \text{var}_\theta}$$

$$\text{schatting variantie faseruis} \quad \frac{1}{K \cdot L} \cdot \text{tr}(\theta \cdot \theta^T) = 0.103 \quad \text{var}_\theta = 0.1$$

$$\theta_{\text{tot},m} := \theta_{k,m} + \text{offset}$$



ontvangen signaal (geen additieve ruis)

$$r_{\text{lin}}_{i,m} := \theta_{\text{tot}}_{\text{index}_i,m}$$

$$r_{i,m} := \exp(j \cdot \theta_{\text{tot}}_{\text{index}_i,m})$$

correctie voor tijdsgemiddelde

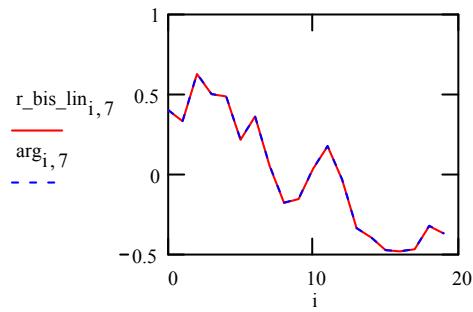
$$r_{\text{avg}}_m := \frac{1}{K_P} \cdot \sum_i r_{\text{lin}}_{i,m}$$

$$\arg_{\text{avg}}_m := \arg \left(\sum_i r_{i,m} \right)$$

$$r_{\text{bis-lin}}_{i,m} := r_{\text{lin}}_{i,m} - r_{\text{avg}}_m$$

$$r_{\text{bis}}_{i,m} := r_{i,m} \cdot \exp(-j \cdot \arg_{\text{avg}}_m)$$

$$\arg_{i,m} := \arg(r_{\text{bis}}_{i,m})$$



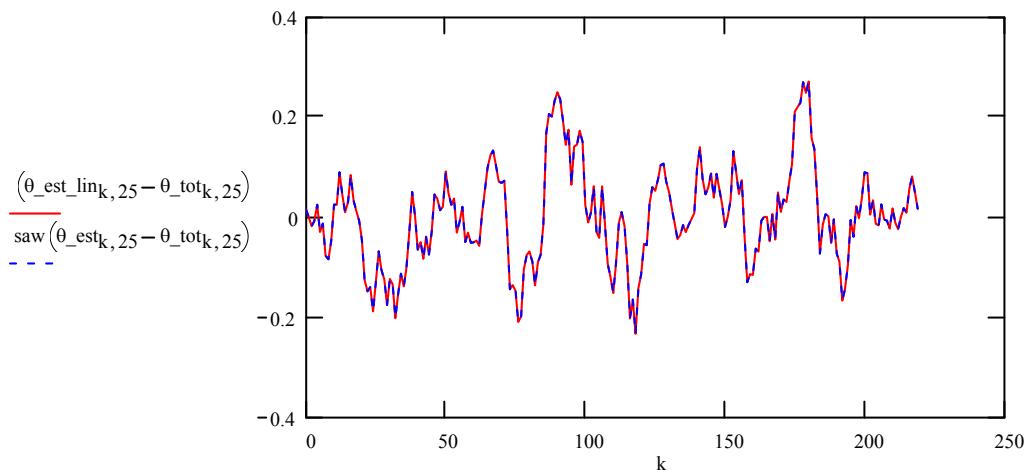
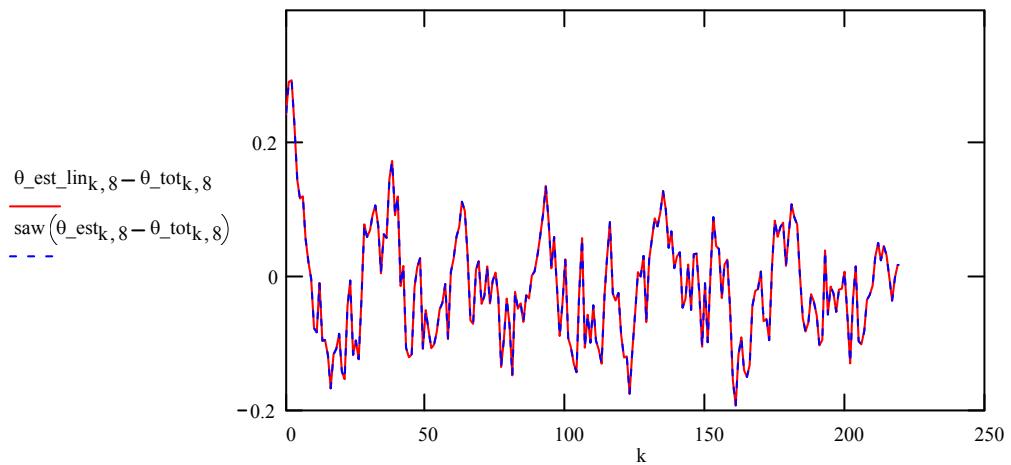
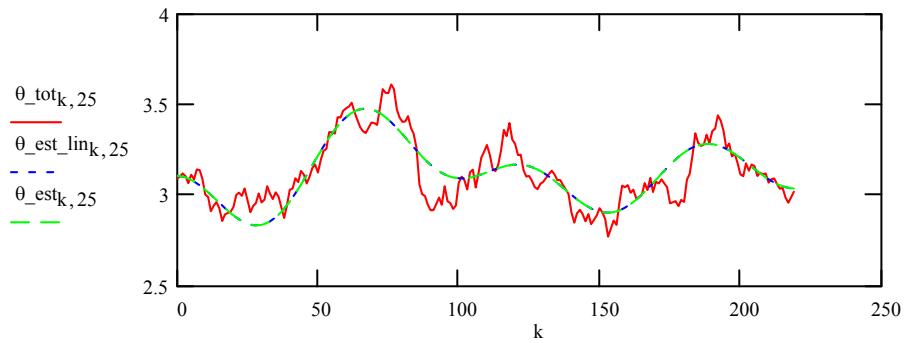
schatting

$$\theta_{\text{est1-lin}} := (\psi \cdot \psi^T \cdot r_{\text{bis-lin}}) \cdot \frac{K}{K_P}$$

$$\theta_{\text{est1}} := \psi \cdot \psi^T \cdot \arg \cdot \frac{K}{K_P}$$

$$\theta_{\text{est-lin}}_{k,m} := \theta_{\text{est1-lin}}_{k,m} + r_{\text{avg}}_m$$

$$\theta_{\text{est}}_{k,m} := \theta_{\text{est1}}_{k,m} + \arg_{\text{avg}}_m$$



$$\text{var_est_lin} := \frac{1}{K \cdot L} \cdot \text{tr} \left[(\theta_{\text{tot}} - \theta_{\text{est_lin}}) \cdot (\theta_{\text{tot}} - \theta_{\text{est_lin}})^T \right]$$

$$\text{var_est_lin} = 8.40245 \cdot 10^{-3}$$

$$\text{var_est} := \frac{1}{K \cdot L} \cdot \text{tr} \left(\overrightarrow{\text{saw}(\theta_{\text{tot}} - \theta_{\text{est}})} \cdot \overrightarrow{\text{saw}(\theta_{\text{tot}} - \theta_{\text{est}})}^T \right)$$

$$\text{var_est} = 8.40245 \cdot 10^{-3}$$

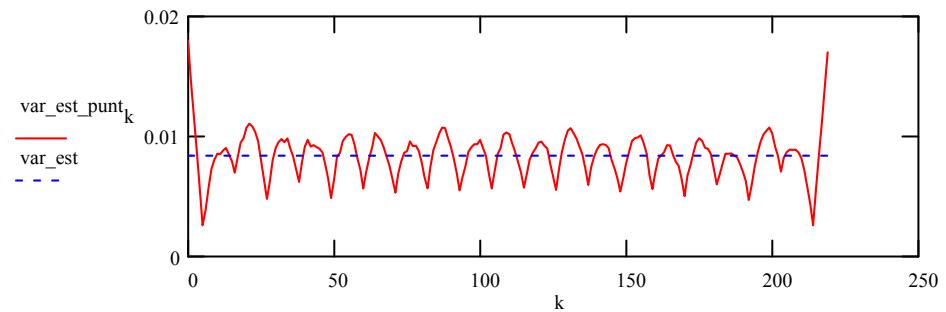
$$K = 220$$

$$K_P = 20$$

$$N = 10$$

$$\text{var_theta} = 0.1$$

$$\text{var_est_punt}_k := \frac{1}{L} \cdot \text{tr} \left[\left(\overrightarrow{\text{saw}(\theta_{\text{tot}} - \theta_{\text{est}})}^T \right)^{<k>} \cdot \left(\overrightarrow{\text{saw}(\theta_{\text{tot}} - \theta_{\text{est}})}^T \right)^{<k>} \right]$$



variantie over een blok wordt minimum op de posities van de pilootsymbolen